

The new  
synchronous linear motors

The designer`s dream!

Low power losses, high dynamics!



## LMS-P

High thrust combined with

- Little cogging
- Little moving mass
- Very high efficiency resulting in
- Little heat dissipation



Stage with LMS-P motor

# LMS-P -35 and -58

permanent excited synchronous linear motors  
with multi-phase windings for  $U_{ZW\ amx} 700\ V$   
for standard servo amplifiers

The new, compact  
motion drive from BOB

Order-No.	Force		Primary unit				Secondary unit			Heat sink	
	$F_{c\ 130^{\circ}C}$ (N)	$F_{max}$ (N)	$L_P$ (mm)	$B_P$ (mm)	$H_P$ (mm)	$m_P$ (kg)	$B_s$ (mm)	$H_s$ (mm)	$m_s$ (kg/m)	$H_c$ (mm)	$m_c$ (kg)
LMS-P 35-017 / 160 -X-aaa-S	53	210	184	44	25,0	1,0	45	10,4	2,4	20	0,3
LMS-P 35-035 / 160 -X-aaa-S	130	430	184	64	25,0	1,5	70	11,4	4,5	20	0,4
LMS-P 35-035 / 320 -X-aaa-S	240	870	344	64	25,0	2,7	70	11,4	4,5	20	0,8
LMS-P 35-052 / 160 -X-aaa-S	200	640	184	84	25,0	2,0	90	11,4	6,0	20	0,6
LMS-P 35-052 / 320 -X-aaa-S	380	1290	344	84	25,0	3,6	90	11,4	6,0	20	1,1
LMS-P 35-070 / 160 -X-aaa-S	280	870	184	104	25,0	2,5	100	11,4	7,1	20	0,7
LMS-P 35-070 / 320 -X-aaa-S	540	1740	344	104	25,0	4,6	100	11,4	7,1	20	1,3
LMS-P 35-070 / 480 -X-aaa-S	810	2600	504	104	25,0	6,7	100	11,4	7,1	20	2,0
LMS-P 35-105 / 160 -X-aaa-S	440	1300	184	139	25,0	3,5	140	11,4	10,1	20	0,9
LMS-P 35-105 / 320 -X-aaa-S	840	2600	344	139	25,0	6,5	140	11,4	10,1	20	1,8
LMS-P 35-105 / 480 -X-aaa-S	1250	3910	504	139	25,0	9,5	140	11,4	10,1	20	2,6
LMS-P 35-140 / 160 -X-aaa-S	590	1740	184	174	25,0	4,4	180	13,4	15,9	20	1,2
LMS-P 35-140 / 320 -X-aaa-S	1150	3470	344	174	25,0	8,3	180	13,4	15,9	20	2,2
LMS-P 35-140 / 480 -X-aaa-S	1700	5210	504	174	25,0	12,2	180	13,4	15,9	20	3,3
LMS-P 58-035 / 185 -X-aaa-S	290	500	214	68	45,8	2,9	70	11,4	4,7	20	0,5
LMS-P 58-035 / 370 -X-aaa-S	550	1000	399	68	45,8	5,5	70	11,4	4,7	20	0,9
LMS-P 58-070 / 185 -X-aaa-S	640	1000	214	106	45,8	4,9	100	11,4	7,5	20	0,8
LMS-P 58-070 / 370 -X-aaa-S	1230	2000	399	106	45,8	9,4	100	11,4	7,5	20	1,6
LMS-P 58-070 / 555 -X-aaa-S	1830	3000	584	106	45,8	13,9	100	11,4	7,5	20	2,3
LMS-P 58-105 / 185 -X-aaa-S	990	1500	214	141	45,8	6,9	140	11,4	10,8	20	1,1
LMS-P 58-105 / 370 -X-aaa-S	1920	3000	399	141	45,8	13,3	140	11,4	10,8	20	2,1
LMS-P 58-105 / 555 -X-aaa-S	2840	4500	584	141	45,8	19,7	140	11,4	10,8	20	3,0
LMS-P 58-140 / 185 -X-aaa-S	1300	2000	214	176	45,8	8,9	180	13,4	16,8	20	1,4
LMS-P 58-140 / 370 -X-aaa-S	2600	4000	399	176	45,8	17,2	180	13,4	16,8	20	2,6
LMS-P 58-140 / 555 -X-aaa-S	3900	6010	584	176	45,8	25,5	180	13,4	16,8	20	3,8
LMS-P 58-210 / 185 -X-aaa-S	2100	3000	226	246	49,8	15,1	250	15,4	27,9	20	2,0
LMS-P 58-210 / 370 -X-aaa-S	4100	6010	411	246	49,8	28,9	250	15,4	27,9	20	3,8
LMS-P 58-210 / 555 -X-aaa-S	6000	9010	596	246	49,8	42,5	250	15,4	27,9	20	5,5

$F_{c\ 130^{\circ}C}$  = Continuous force ( $C_u : 130^{\circ}C$ ) \*

$F_{max}$  = Maximum force

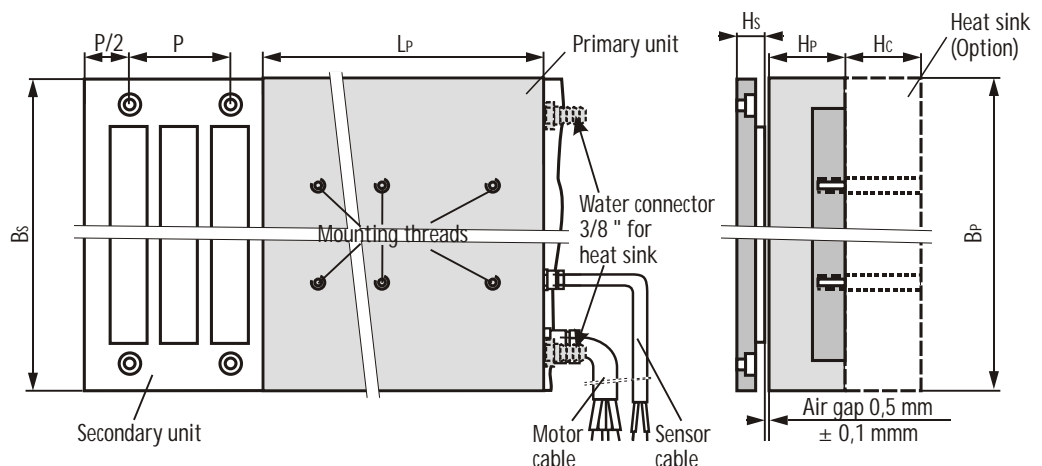
\* with motor fitted to an aluminium heat sink with a surface of  
3 x primary unit surface ( $L_P \times B_P$ ), 12 mm thick, at ambient temperature of  $20^{\circ}C$

$m_P$  = Mass of primary unit

$m_s$  = Mass of secondary unit

$m_c$  = Mass of heat sink

LMS-P 35 Secondary unit	LMS-P 58 Secondary unit
P = 32 mm	P = 37 mm
available length :	available length :
- 64 mm	- 74 mm
- 96 mm	- 111 mm
- 160 mm	- 185 mm
- 288 mm	- 333 mm
- 544 mm	- 629 mm
- 992 mm	- 999 mm



For our wide range of linear and servo motors please ask for additional, detailed information  
Own design, patents and production



## BOB Synchronous linear motor

### Typ LMS-P description and order-key-code

**The primary unit** of LMS-P35 and LMS-P58 is equipped with multi-phase iron-core winding. Due to a special geometry of the magnetic circuit these motors have a high specific power, low "cogging", little mass and small dimensions.

**The secondary unit** is equipped with permanent magnets. Secondary units are available in 6 different lengths (as shown in data-sheet). With these lengths every requested length of stroke is realizable in steps of 32 mm (LMS-P35) respectively 37 mm (LMS-P58). A covering of stainless steel guarantees the mechanical protection of the magnets and makes cleaning easy. Several primary units can be driven independently of one to each other on a single secondary unit.

**The heat-sink** (water cooling) prevents heat transfer into the application (optional).

**The shown data** are valid for fitting of the primary unit to a cooling area of adequate size (minimal three times size of the installation surface, aluminium, 12 mm thick), a winding temperature of 130°C at an ambient temperature of 20°C and natural ventilation.

#### Primary unit

LMS-P XX - YYY / ZZZ - P - pstw - x - m

Type \_\_\_\_\_  
 Code for motor height \_\_\_\_\_  
 Code for motor width \_\_\_\_\_  
 Code for primary length \_\_\_\_\_  
 P = Code for primary unit \_\_\_\_\_  
 Code for number of phases \_\_\_\_\_  
 3 = 3-phase  
 Code for connection \_\_\_\_\_  
 S = Star-connection  
 D = Delta-connection  
 Code for temperature sensor \_\_\_\_\_  
 N = NTC 130°C  
 P = PTC 130°C  
 K = KTY 84  
 Code for winding \_\_\_\_\_  
 Code for magnet \_\_\_\_\_  
 1 = Standard  
 Modification (Standard or Customer with Id.-Nr.) \_\_\_\_\_

#### Secondary unit

LMS-P XX - YYY / \_\_\_ S - aaa - x - m

Type \_\_\_\_\_  
 Code for motor height \_\_\_\_\_  
 Code for motor width \_\_\_\_\_  
 S = Code for secondary unit \_\_\_\_\_  
 Length (mm) \_\_\_\_\_  
 Code for magnet ( 1 = Standard) \_\_\_\_\_  
 Modification (Standard or Customer with Id.-Nr.) \_\_\_\_\_

## BOB synchronous - linear - motor

### Typ LMS-P 35-017 / ...

Primary unit	Symbol	Unit	... / 160 P - 3stC - 1 - S	
			s = D	s = S
Circuit mode				
Continuous force (Cu: 130°C)	F <sub>C 130°C</sub>	N	53	53
Maximum force	F <sub>max</sub>	N	210	210
Continuous power loss (Cu:130°C)	P <sub>v 130°C</sub>	W	39	39
Thermal resistance	R <sub>th</sub>	K/W	2,806	2,806
Motor constant	K <sub>m 20°C</sub>	N/W <sup>1/2</sup>	10,1	10,1
Force constant	K <sub>t</sub>	N/A	27,2	47,1
Back EMF constant	K <sub>e</sub>	Vs/m	15,7	27,2
Time constant electrical	τ <sub>e</sub>	ms	4,2	4,2
Continuous current (Cu: 130°C)	I <sub>c 130°C</sub>	A	1,9	1,1
Peak current	I <sub>max</sub>	A	11,0	6,4
Demagnetising current	I <sub>p</sub>	A	>40	>23
DC-resistance Ph/Ph (20°C)	R	W	4,8	14,4
Inductance Ph/Ph	L	mH	20,3	60,8
Max. permitted input-voltage	Ū <sub>max DC</sub>	V	700	700
Max. speed	v <sub>max</sub>	m/s	15,8	18,2
Force from magnetic attraction	F <sub>mag</sub>	kN	0,35	0,35
Displacement force (deenergised)	F <sub>v</sub>	N	1,1	1,1
Length primary unit	A	mm	184	184
Mass primary unit	m <sub>p</sub>	kg	1,0	1,0
Motor-cable (wire-cross-section)	□	mm <sup>2</sup>	0,75	0,75
Motor-cable (diameter)	∅	mm	10,5	10,5
Motor-cable (PG-locknut diameter)	B	mm	22	22
Secondary unit			... / S -aaa- S	
Pole pitch (N-S)	pp	mm	16	
Mass per meter Secondary unit	m <sub>s</sub>	kg/m	2,4	

Electrical figures apply for sinusoidal commutation and are r.m.s. values or refer to r.m.s.values respectively.

### Connection

#### Cable

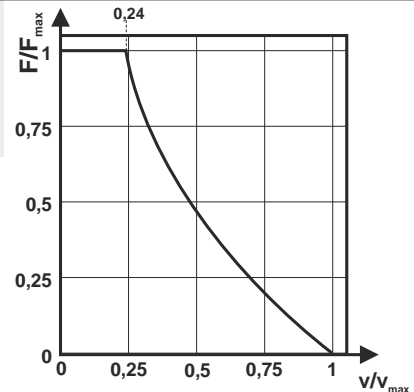
0,6 m long  
 (shielded)  
 4 G 0,75  
 +  
 2 x (2 x 0,34)  
 StD-CY

NTC / 130 °C (t = N)  
 MT : PTC / 130 °C (t = P)  
 KTY 84 - 130 (t = K)

Connector	Code	
Phase U	1 (BK)	BK
Phase V	2 (BK)	BN
Phase W	3 (BK)	BU
PE	GNYE	
MT +	WH	GN
MT -	BN	YE
Shield	WH or "SHIELD"	

$$F_{max} = f(v)$$

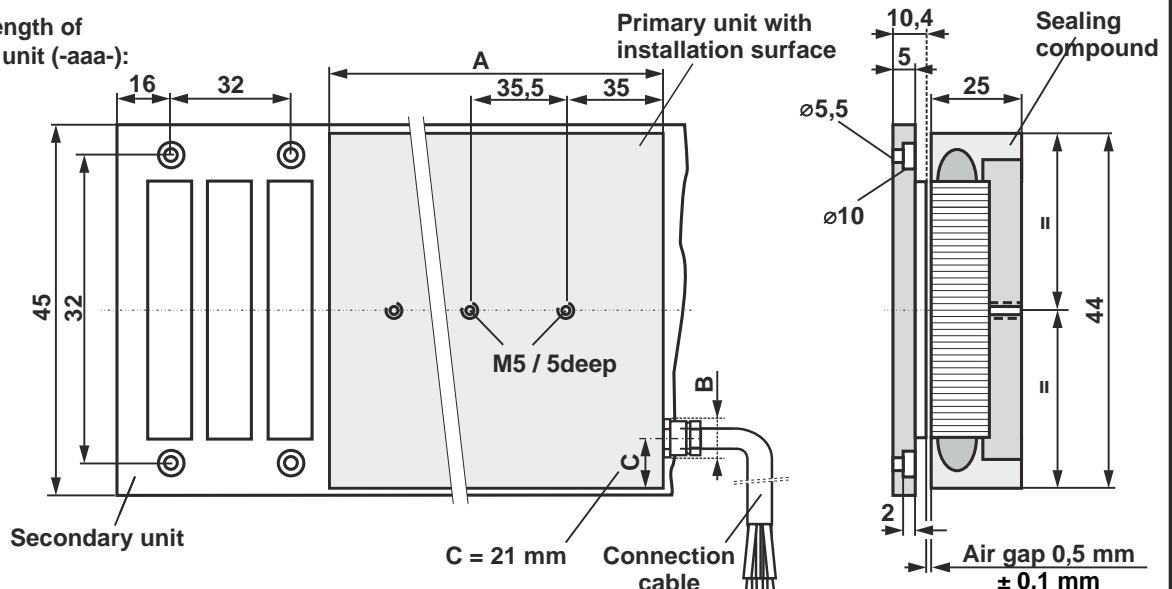
Ū<sub>min DC</sub> : 300 V /  
 520 V  
 Winding-  
 temp.: 130°C



### Dimensions

available length of  
 secondary unit (-aaa-):

- 064 mm
- 096 mm
- 160 mm
- 288 mm
- 544 mm
- 992 mm





## BOB synchronous - linear - motor

### Typ LMS-P 35-052 / ...

Primary unit	Symbol	Unit	... / 160 P - 3stM - 1 - S		... / 320 P - 3stM - 1 - S	
			s = D	s = S	s = D	s = S
Circuit mode						
Continuous force (Cu: 130°C)	F <sub>C 130°C</sub>	N	200	200	380	380
Maximum force	F <sub>max</sub>	N	640	640	1290	1290
Continuous power loss (Cu:130°C)	P <sub>v 130°C</sub>	W	126	126	227	227
Thermal resistance	R <sub>th</sub>	K/W	0,918	0,918	0,491	0,491
Motor constant	K <sub>m 20°C</sub>	N/W <sup>1/2</sup>	21,3	21,3	30,2	30,2
Force constant	K <sub>t</sub>	N/A	29,4	50,9	58,8	101,8
Back EMF constant	K <sub>e</sub>	Vs/m	17,0	29,4	33,9	58,8
Time constant electrical	τ <sub>e</sub>	ms	6,1	6,1	6,1	6,1
Continuous current (Cu: 130°C)	I <sub>c 130°C</sub>	A	6,8	3,9	6,5	3,7
Peak current	I <sub>max</sub>	A	31,1	18,0	31,4	18,1
Demagnetising current	I <sub>p</sub>	A	>110	>65	>110	>65
DC-resistance Ph/Ph (20°C)	R	W	1,3	3,8	2,5	7,6
Inductance Ph/Ph	L	mH	7,7	23,2	15,4	46,3
Max. permitted input-voltage	Ū <sub>max DC</sub>	V	700	700	700	700
Max. speed	v <sub>max</sub>	m/s	14,6	16,8	7,3	8,4
Force from magnetic attraction	F <sub>mag</sub>	kN	1,06	1,06	2,13	2,13
Displacement force (deenergised)	F <sub>v</sub>	N	3,3	3,3	6,7	6,7
Length primary unit	A	mm	184	184	344	344
Mass primary unit	m <sub>p</sub>	kg	2,0	2,0	3,6	3,6
Motor-cable (wire-cross-section)	□	mm <sup>2</sup>	1,5	1,5	1,5	1,5
Motor-cable (diameter)	∅	mm	12,1	12,1	12,1	12,1
Motor-cable (PG-locknut diameter)	B	mm	22	22	22	22
Secondary unit			... / S -aaa- S			
Pole pitch (N-S)	pp	mm	16			
Mass per meter Secondary unit	m <sub>s</sub>	kg/m	6,0			

Electrical figures apply for sinusoidal commutation and are r.m.s. values or refer to r.m.s.values respectively.

### Connection

#### Motor

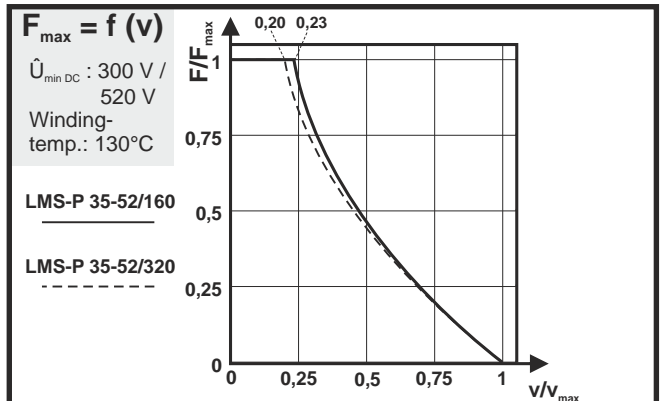
(shielded)  
 0,6 m long

#### Sensor

(shielded)  
 0,6 m long  
 : 8,6 mm

NTC / 130 °C (t = N)  
 MT : PTC / 130 °C (t = P)  
 KTY 84 - 130 (t = K)

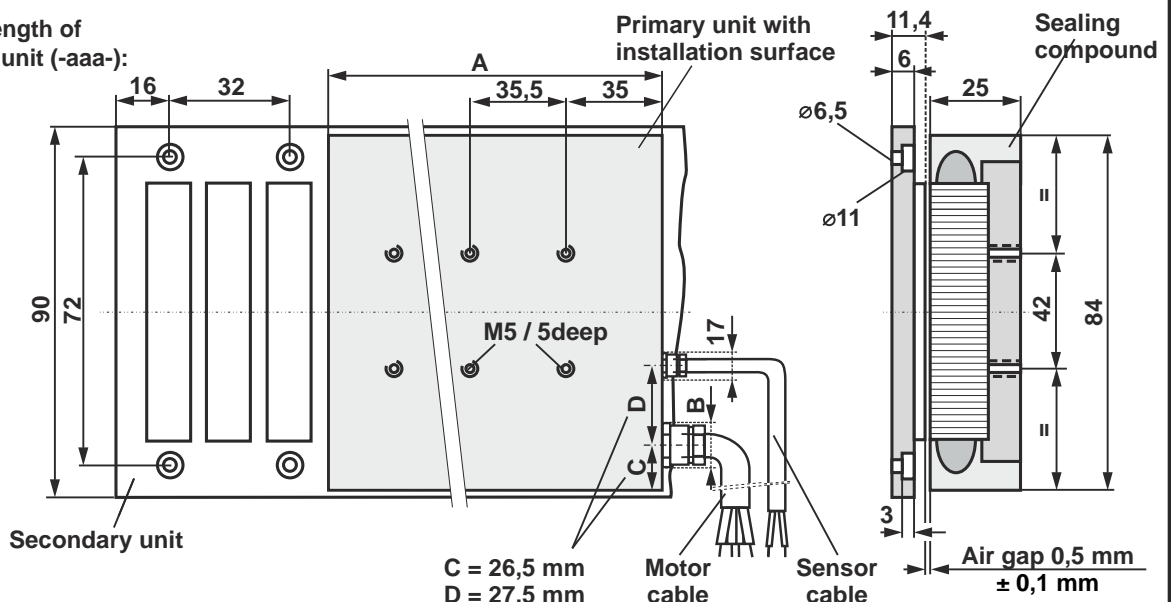
Connector	Code
Phase U	1 (BK) BK
Phase V	2 (BK) BN
Phase W	3 (BK) BU
PE	GNYE
MT +	BN
MT -	BU
Shield	WH or "SHIELD"



### Dimensions

available length of secondary unit (-aaa-):

- 064 mm
- 096 mm
- 160 mm
- 288 mm
- 544 mm
- 992 mm



Performance data are tolerated +/-10%. Measurements in mm.

The rights are reserved to make modification in the general sense of technical progress without previous notice.

## BOB synchronous - linear - motor

### Typ LMS-P 35-070 / ...

Primary unit	Symbol	Unit	... / 160 P - 3stO - 1 - S	... / 320 P - 3stO - 1 - S	... / 480 P - 3stO - 1 - S	... / 160 P - 3stO - 1 - S	... / 320 P - 3stO - 1 - S	... / 480 P - 3stO - 1 - S
Circuit mode			s = D	s = S	s = D	s = S	s = D	s = S
Continuous force (Cu: 130°C)	$F_C 130^\circ C$	N	280	280	540	540	810	810
Maximum force	$F_{max}$	N	870	870	1740	1740	2600	2600
Continuous power loss (Cu:130°C)	$P_v 130^\circ C$	W	160	160	299	299	448	448
Thermal resistance	$R_{th}$	K/W	0,682	0,682	0,365	0,365	0,249	0,249
Motor constant	$K_m 20^\circ C$	N/W <sup>1/2</sup>	26,5	26,5	37,4	37,4	45,8	45,8
Force constant	$K_t$	N/A	29,7	51,4	59,4	102,8	89,0	154,1
Back EMF constant	$K_e$	Vs/m	17,1	29,7	34,2	59,3	51,4	89,0
Time constant electrical	$\tau_e$	ms	7,0	7,0	7,0	7,0	7,0	7,0
Continuous current (Cu: 130°C)	$I_c 130^\circ C$	A	9,4	5,4	9,1	5,3	9,1	5,3
Peak current	$I_{max}$	A	41,9	24,2	41,9	24,2	41,7	24,1
Demagnetising current	$I_p$	A	>150	>85	>150	>85	>150	>85
DC-resistance Ph/Ph (20°C)	R	W	0,8	2,5	1,7	5,0	2,5	7,5
Inductance Ph/Ph	L	mH	5,8	17,5	11,7	35,1	17,5	52,6
Max. permitted input-voltage	$\hat{U}_{max DC}$	V	700	700	700	700	700	700
Max. speed	$v_{max}$	m/s	14,4	16,7	7,2	8,3	4,8	5,6
Force from magnetic attraction	$F_{mag}$	kN	1,43	1,43	2,86	2,86	4,30	4,30
Displacement force (deenergised)	$F_v$	N	4,5	4,5	9,0	9,0	13,4	13,4
Length primary unit	A	mm	184	184	344	344	504	504
Mass primary unit	$m_p$	kg	2,5	2,5	4,6	4,6	6,7	6,7
Motor-cable (wire-cross-section)	$\square$	mm <sup>2</sup>	1,5	1,5	1,5	1,5	1,5	1,5
Motor-cable (diameter)	$\emptyset$	mm	12,1	12,1	12,1	12,1	12,1	12,1
Motor-cable (PG-locknut diameter)	B	mm	22	22	22	22	22	22
Secondary unit			... / S -aaa- S					
Pole pitch (N-S)	pp	mm	16					
Mass per meter Secondary unit	$m_s$	kg/m	7,1					

Electrical figures apply for sinusoidal commutation and are r.m.s. values or refer to r.m.s.values respectively.

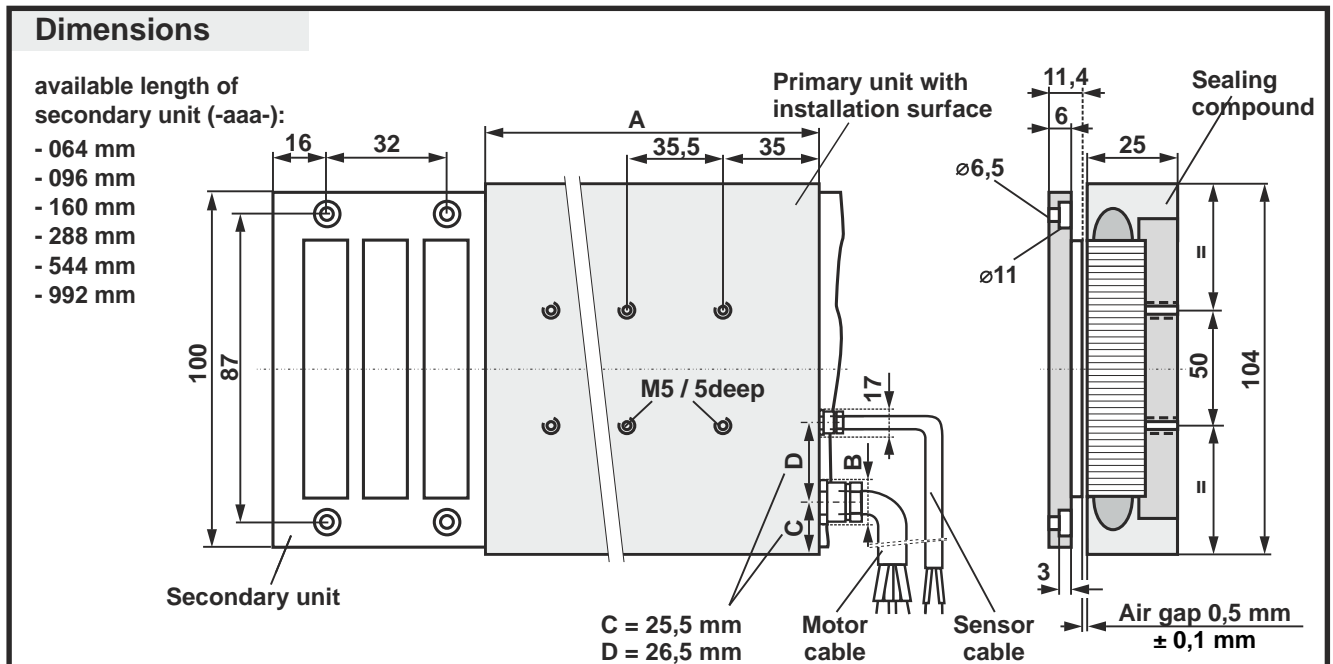
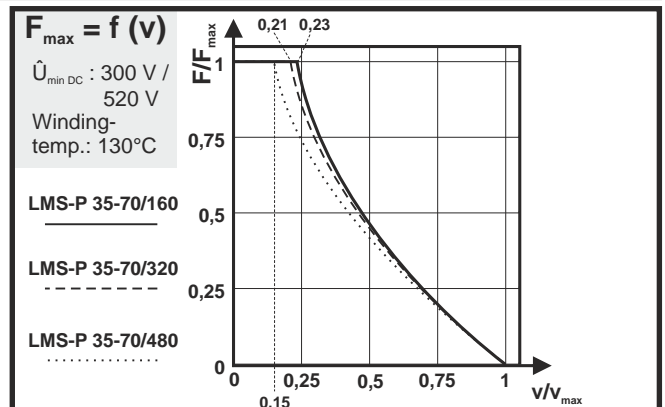
### Connection

NTC / 130 °C (t = N)  
 MT : PTC / 130 °C (t = P)  
 KTY 84 - 130 (t = K)

Connector	Code
Phase U	1 (BK) BK
Phase V	2 (BK) BN
Phase W	3 (BK) BU
PE	GNYE
MT +	BN
MT -	BU
Shield	WH or "SHIELD"

**Motor**  
 (shielded)  
 0,6 m long

**Sensor**  
 (shielded)  
 0,6 m long  
 : 8,6 mm



Performance data are tolerated +/-10%. Measurements in mm.

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## BOB synchronous - linear - motor

### Typ LMS-P 35-105 / ...

Primary unit	Symbol	Unit	... / 160 P - 3stS - 1 - S	... / 320 P - 3stS - 1 - S	... / 480 P - 3stS - 1 - S
Circuit mode			s = D	s = S	s = D
Continuous force (Cu: 130°C)	F <sub>C 130°C</sub>	N		440	840
Maximum force	F <sub>max</sub>	N		1300	2600
Continuous power loss (Cu:130°C)	P <sub>v 130°C</sub>	W		247	450
Thermal resistance	R <sub>th</sub>	K/W		0,454	0,243
Motor constant	K <sub>m 20°C</sub>	N/W <sup>1/2</sup>		33,5	47,4
Force constant	K <sub>t</sub>	N/A		44,7	89,4
Back EMF constant	K <sub>e</sub>	Vs/m		25,8	51,6
Time constant electrical	τ <sub>e</sub>	ms		7,5	7,5
Continuous current (Cu: 130°C)	I <sub>c 130°C</sub>	A		9,8	9,4
Peak current	I <sub>max</sub>	A		41,5	41,5
Demagnetising current	I <sub>p</sub>	A		>150	>150
DC-resistance Ph/Ph (20°C)	R	W		1,2	2,4
Inductance Ph/Ph	L	mH		8,9	17,7
Max. permitted input-voltage	Ū <sub>max DC</sub>	V		700	700
Max. speed	v <sub>max</sub>	m/s		19,2	9,6
Force from magnetic attraction	F <sub>mag</sub>	kN		2,15	4,30
Displacement force (deenergised)	F <sub>v</sub>	N		6,7	13,4
Length primary unit	A	mm		184	344
Mass primary unit	m <sub>p</sub>	kg		3,5	6,5
Motor-cable (wire-cross-section)	□	mm <sup>2</sup>		1,5	1,5
Motor-cable (diameter)	∅	mm		12,1	12,1
Motor-cable (PG-locknut diameter)	B	mm		22	22
Secondary unit			... / S -aaa- S		
Pole pitch (N-S)	pp	mm	16		
Mass per meter Secondary unit	m <sub>s</sub>	kg/m	10,1		

Electrical figures apply for sinusoidal commutation and are r.m.s. values or refer to r.m.s.values respectively.

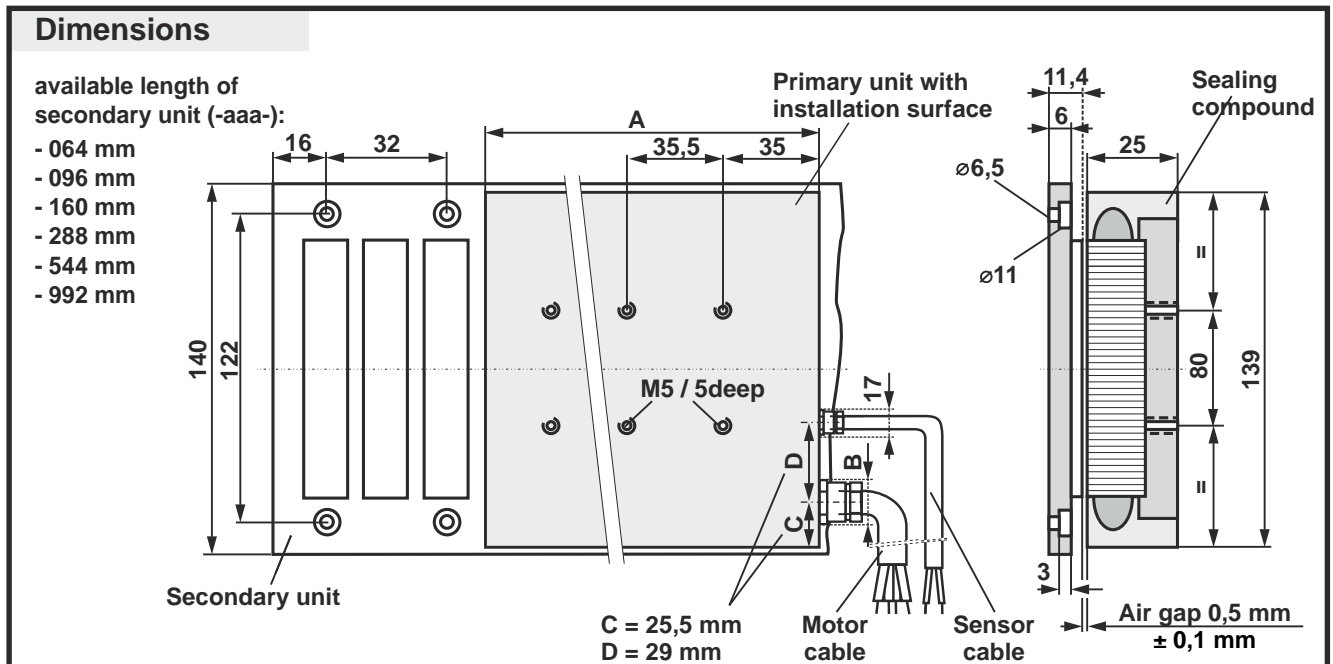
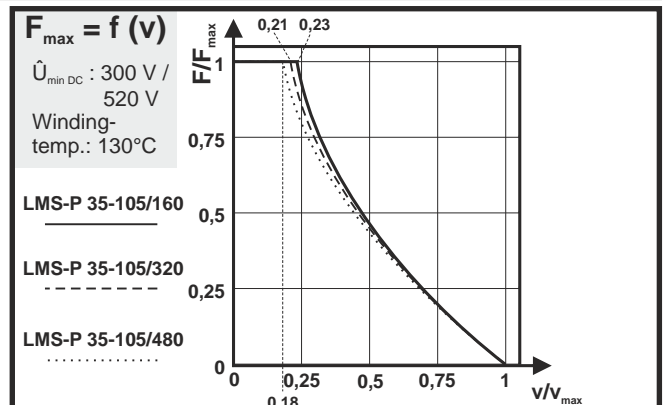
### Connection

NTC / 130 °C (t = N)  
 MT : PTC / 130 °C (t = P)  
 KTY 84 - 130 (t = K)

Connector	Code
Phase U	1 (BK) BK
Phase V	2 (BK) BN
Phase W	3 (BK) BU
PE	GNYE
MT +	BN
MT -	BU
Shield	WH or "SHIELD"

**Motor**  
 (shielded)  
 0,6 m long

**Sensor**  
 (shielded)  
 0,6 m long  
 : 8,6 mm



Performance data are tolerated +/-10%. Measurements in mm.

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## BOB synchronous - linear - motor

### Typ LMS-P 58-035 / ...

Primary unit	Symbol	Unit	... / 185 P - 3st1 - 1 - S		... / 370 P - 3st1 - 1 - S	
			s = D	s = S	s = D	s = S
Circuit mode						
Continuous force (Cu: 130°C)	F <sub>C 130°C</sub>	N	290	290	550	550
Maximum force	F <sub>max</sub>	N	500	500	1000	1000
Continuous power loss (Cu:130°C)	P <sub>v 130°C</sub>	W	116	116	208	208
Thermal resistance	R <sub>th</sub>	K/W	0,975	0,975	0,523	0,523
Motor constant	K <sub>m 20°C</sub>	N/W <sup>1/2</sup>	32,2	32,2	45,6	45,6
Force constant	K <sub>t</sub>	N/A	27,1	46,9	54,1	93,7
Back EMF constant	K <sub>e</sub>	Vs/m	15,6	27,1	31,2	54,1
Time constant electrical	τ <sub>e</sub>	ms	20,9	20,9	20,9	20,9
Continuous current (Cu: 130°C)	I <sub>c 130°C</sub>	A	10,7	6,2	10,2	5,9
Peak current	I <sub>max</sub>	A	26,4	15,2	26,4	15,2
Demagnetising current	I <sub>p</sub>	A	>90	>55	>90	>55
DC-resistance Ph/Ph (20°C)	R	W	0,5	1,4	0,9	2,8
Inductance Ph/Ph	L	mH	9,8	29,5	19,6	58,9
Max. permitted input-voltage	Ū <sub>max DC</sub>	V	700	700	700	700
Max. speed	v <sub>max</sub>	m/s	15,8	18,3	7,9	9,1
Force from magnetic attraction	F <sub>mag</sub>	kN	0,88	0,88	1,76	1,76
Displacement force (deenergised)	F <sub>v</sub>	N	2,6	2,6	5,2	5,2
Length primary unit	A	mm	214	214	399	399
Mass primary unit	m <sub>p</sub>	kg	2,9	2,9	5,5	5,5
Motor-cable (wire-cross-section)	□	mm <sup>2</sup>	1,5	1,5	1,5	1,5
Motor-cable (diameter)	∅	mm	12,1	12,1	12,1	12,1
Motor-cable (PG-locknut diameter)	B	mm	22	22	22	22
Secondary unit			... / S -aaa- S			
Pole pitch (N-S)	pp	mm	18,5			
Mass per meter Secondary unit	m <sub>s</sub>	kg/m	4,7			

Electrical figures apply for sinusoidal commutation and are r.m.s. values or refer to r.m.s.values respectively.

### Connection

#### Motor

(shielded)  
 0,6 m long

#### Sensor

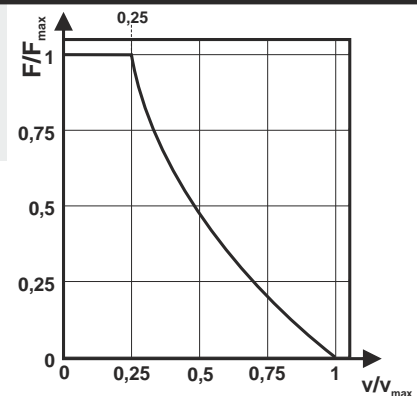
(shielded)  
 0,6 m long  
 : 8,6 mm

NTC / 130 °C (t = N)  
 MT : PTC / 130 °C (t = P)  
 KTY 84 - 130 (t = K)

Connector	Code
Phase U	1 (BK) BK
Phase V	2 (BK) BN
Phase W	3 (BK) BU
PE	GNYE
MT +	BN
MT -	BU
Shield	WH or "SHIELD"

$$F_{max} = f(v)$$

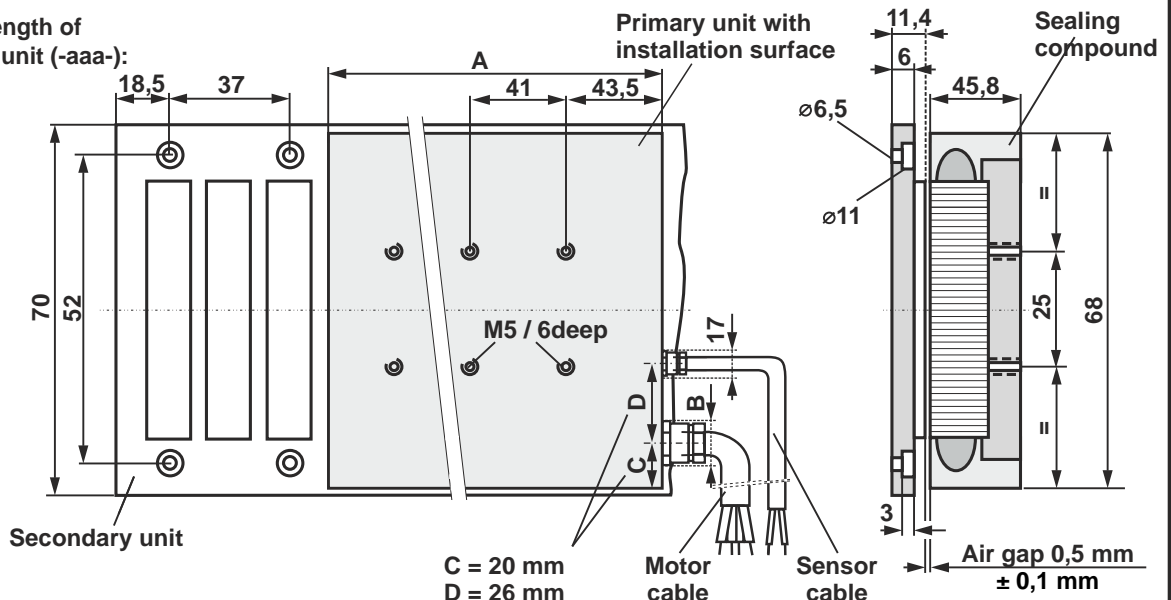
Ū<sub>min DC</sub> : 300 V / 520 V  
 Winding-temp.: 130°C



### Dimensions

available length of secondary unit (-aaa-):

- 074 mm
- 111 mm
- 185 mm
- 333 mm
- 629 mm
- 999 mm



Performance data are tolerated +/-10%. Measurements in mm.

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## BOB synchronous - linear - motor

### Typ LMS-P 58-105 / ...

Primary unit	Symbol	Unit	... / 185 P - 3st3 - 1 - S	... / 370 P - 3st3 - 1 - S	... / 555 P - 3st3 - 1 - S	... / S -aaa- S		
Circuit mode			s = D	s = S	s = D	s = S		
Continuous force (Cu: 130°C)	$F_C 130^\circ C$	N	990	990	1920	1920	2840	2840
Maximum force	$F_{max}$	N	1500	1500	3000	3000	4500	4500
Continuous power loss (Cu:130°C)	$P_V 130^\circ C$	W	337	337	635	635	926	926
Thermal resistance	$R_{th}$	K/W	0,325	0,325	0,174	0,174	0,119	0,119
Motor constant	$K_m 20^\circ C$	N/W <sup>1/2</sup>	64,5	64,5	91,2	91,2	111,7	111,7
Force constant	$K_t$	N/A	36,4	63,1	72,9	126,2	109,3	189,3
Back EMF constant	$K_e$	Vs/m	21,0	36,4	42,1	72,9	63,1	109,3
Time constant electrical	$\tau_e$	ms	27,8	27,8	27,8	27,8	28,0	28,0
Continuous current (Cu: 130°C)	$I_C 130^\circ C$	A	27,2	15,7	26,4	15,2	26,0	15,0
Peak current	$I_{max}$	A	58,8	34,0	58,8	34,0	58,8	34,0
Demagnetising current	$I_P$	A	>210	>120	>210	126,3	>210	>120
DC-resistance Ph/Ph (20°C)	R	W	0,2	0,6	0,4	1,3	0,6	1,9
Inductance Ph/Ph	L	mH	5,9	17,8	11,9	35,6	17,8	53,4
Max. permitted input-voltage	$\hat{U}_{max DC}$	V	700	700	700	700	700	700
Max. speed	$v_{max}$	m/s	11,8	13,6	5,9	6,8	3,9	4,5
Force from magnetic attraction	$F_{mag}$	kN	2,64	2,64	5,28	5,28	7,92	7,92
Displacement force (deenergised)	$F_v$	N	7,8	7,8	15,5	15,5	23,3	23,3
Length primary unit	A	mm	214	214	399	399	584	584
Mass primary unit	$m_p$	kg	6,9	6,9	13,3	13,3	19,7	19,7
Motor-cable (wire-cross-section)	$\square$	mm <sup>2</sup>	4,0	2,5	4,0	2,5	4,0	2,5
Motor-cable (diameter)	$\emptyset$	mm	17,4	14,6	17,4	14,6	17,4	14,6
Motor-cable (PG-locknut diameter)	B	mm	34	27	34	27	34	27
Secondary unit								
Pole pitch (N-S)	pp	mm					18,5	
Mass per meter Secondary unit	$m_s$	kg/m					10,8	

Electrical figures apply for sinusoidal commutation and are r.m.s. values or refer to r.m.s.values respectively.

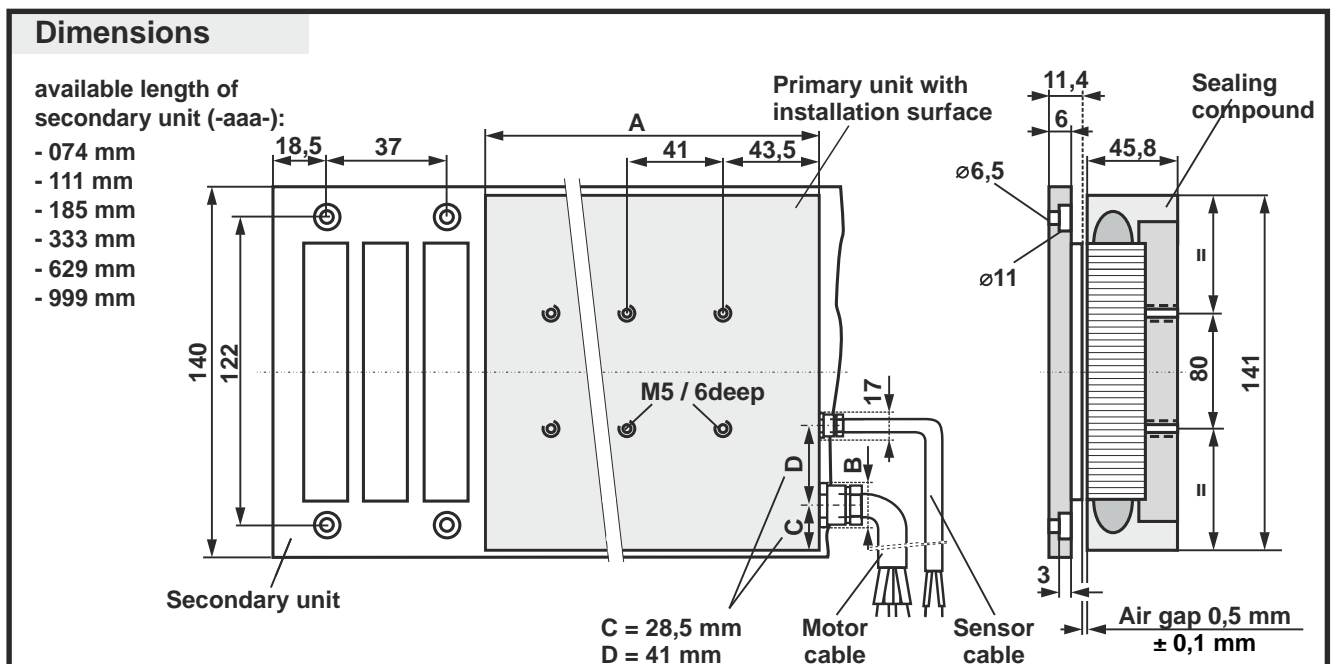
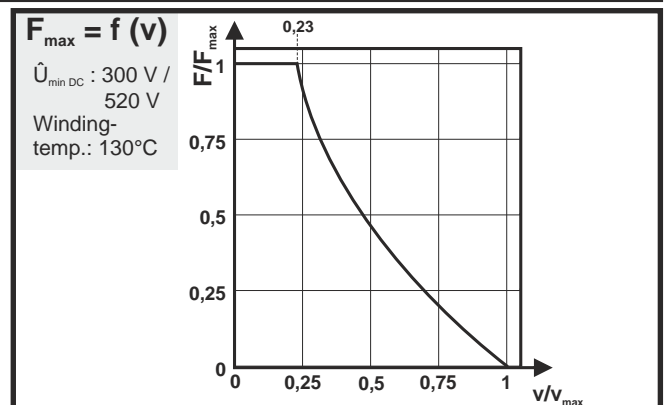
### Connection

NTC / 130 °C (t = N)  
 MT : PTC / 130 °C (t = P)  
 KTY 84 - 130 (t = K)

Connector	Code
Phase U	1 (BK) BK
Phase V	2 (BK) BN
Phase W	3 (BK) BU
PE	GNYE
MT +	BN
MT -	BU
Shield	WH or "SHIELD"

**Motor**  
 (shielded)  
 0,6 m long

**Sensor**  
 (shielded)  
 0,6 m long  
 : 8,6 mm



Performance data are tolerated +/-10%. Measurements in mm.

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## BOB synchronous - linear - motor

### Typ LMS-P 58-140 / ...

Primary unit	Symbol	Unit	... / 185 P - 3st3 - 1 - S	... / 370 P - 3st3 - 1 - S	... / 555 P - 3st3 - 1 - S
Circuit mode			s = D	s = S	s = D
Continuous force (Cu: 130°C)	$F_C 130^\circ C$	N	1300	1300	3900
Maximum force	$F_{max}$	N	2000	2000	6010
Continuous power loss (Cu:130°C)	$P_v 130^\circ C$	W	420	420	1260
Thermal resistance	$R_{th}$	K/W	0,244	0,244	0,089
Motor constant	$K_m 20^\circ C$	N/W <sup>1/2</sup>	75,9	75,9	131,5
Force constant	$K_t$	N/A	48,6	84,1	145,7
Back EMF constant	$K_e$	Vs/m	28,1	48,6	84,1
Time constant electrical	$\tau_e$	ms	28,9	28,9	28,9
Continuous current (Cu: 130°C)	$I_c 130^\circ C$	A	26,8	15,5	26,8
Peak current	$I_{max}$	A	58,8	34,0	58,9
Demagnetising current	$I_p$	A	>210	>120	>210
DC-resistance Ph/Ph (20°C)	R	W	0,3	0,8	0,8
Inductance Ph/Ph	L	mH	7,9	23,7	23,7
Max. permitted input-voltage	$\hat{U}_{max DC}$	V	700	700	700
Max. speed	$v_{max}$	m/s	8,8	10,2	2,9
Force from magnetic attraction	$F_{mag}$	kN	3,52	3,52	10,56
Displacement force (deenergised)	$F_v$	N	10,4	10,4	31,1
Length primary unit	A	mm	214	214	584
Mass primary unit	$m_p$	kg	8,9	8,9	25,5
Motor-cable (wire-cross-section)	$\square$	mm <sup>2</sup>	4,0	2,5	4,0
Motor-cable (diameter)	$\emptyset$	mm	17,4	14,6	17,4
Motor-cable (PG-locknut diameter)	B	mm	34	27	34
Secondary unit			... / S -aaa- S		
Pole pitch (N-S)	pp	mm	18,5		
Mass per meter Secondary unit	$m_s$	kg/m	16,8		

Electrical figures apply for sinusoidal commutation and are r.m.s. values or refer to r.m.s.values respectively.

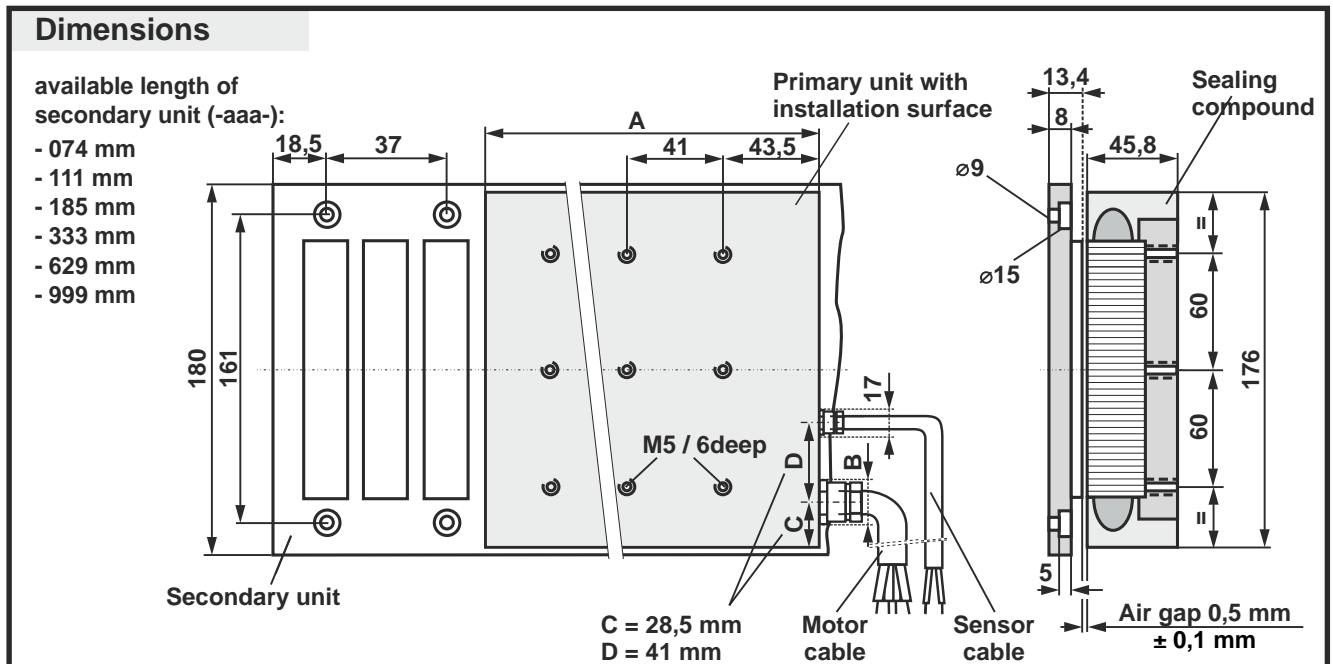
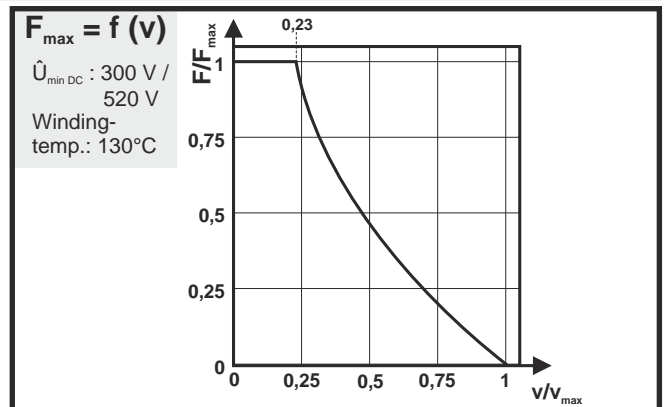
**Connection**

NTC / 130 °C (t = N)  
 MT : PTC / 130 °C (t = P)  
 KTY 84 - 130 (t = K)

Connector	Code
Phase U	1 (BK) BK
Phase V	2 (BK) BN
Phase W	3 (BK) BU
PE	GNYE
MT +	BN
MT -	BU
Shield	WH or "SHIELD"

**Motor**  
 (shielded)  
 0,6 m long

**Sensor**  
 (shielded)  
 0,6 m long  
 : 8,6 mm



Performance data are tolerated +/-10%. Measurements in mm.

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